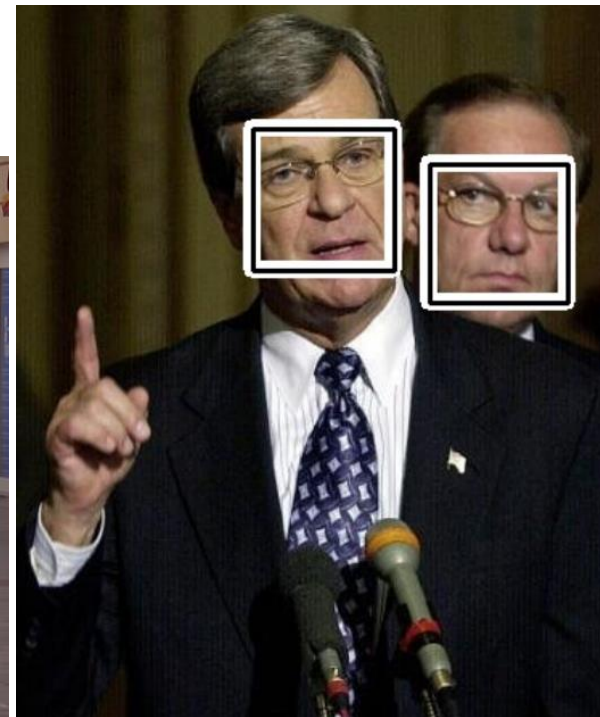
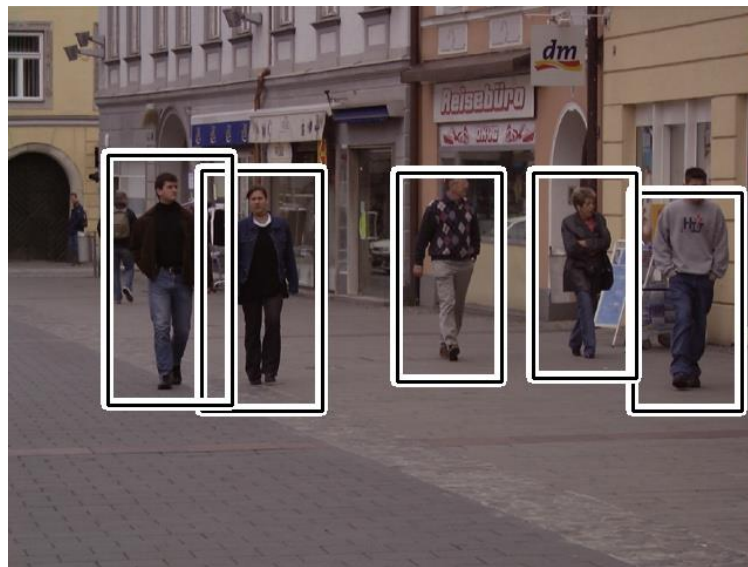
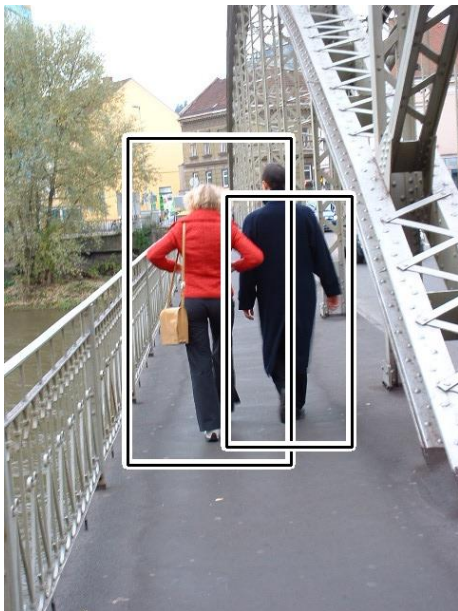


# Object/Face Detection

What is the output of object detection methods?

- Position of the object of interest
- Scale of the object of interest



# Object/Face Detection

- **Haar**

- **Cascade classifier in OpenCV**

- Paul Viola and Michael Jones

- Rapid Object Detection using a Boosted Cascade of Simple Features

- HOG

- LBP

- SIFT, SURF

- CNNs

- R-CNNs/YOLO/SSD

Traditional Approaches  
(sliding window)

KeyPoints

Deep Learning Approach

## Intro into Face Detection

- **Sliding Window**
- In general, the sliding window technique represents the popular and successful approach for object detection. The main idea of this approach is that the input image is scanned by a rectangular window at multiple scales. The result of the scanning process is a large number of various sub-windows. A vector of features is extracted from each sub-window. The vector is then used as an input for the classifier (e.g. SVM classifier).
- During the classification process, some sub-windows are marked as the objects. Using the sliding window approach, the multiple positive detections may appear, especially around the objects of interest

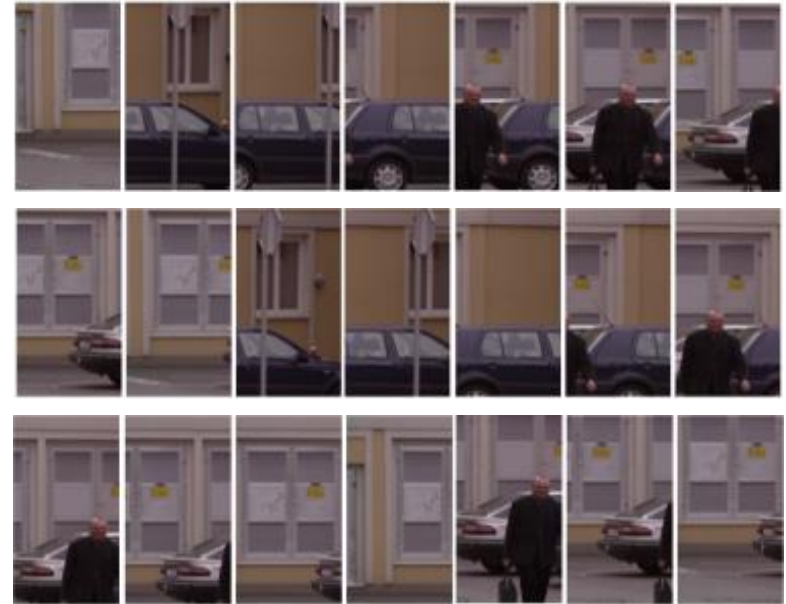
## Intro into Face Detection

- **Sliding Window**
- These detections are merged to the final bounding box that represents the resulting detection.
- The classifier that determines each sub-window is trained over the training set that consists of positive and negative images.
- The key point is to find what values (features) should be used to effectively encode the image inside the sliding window.

# Face Detection

## Intro into Face Detection

- Sliding Window



# Face Detection

## Intro into Face Detection

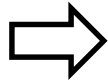
- Sliding Window



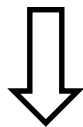
# Face Detection

## Intro into Face Detection

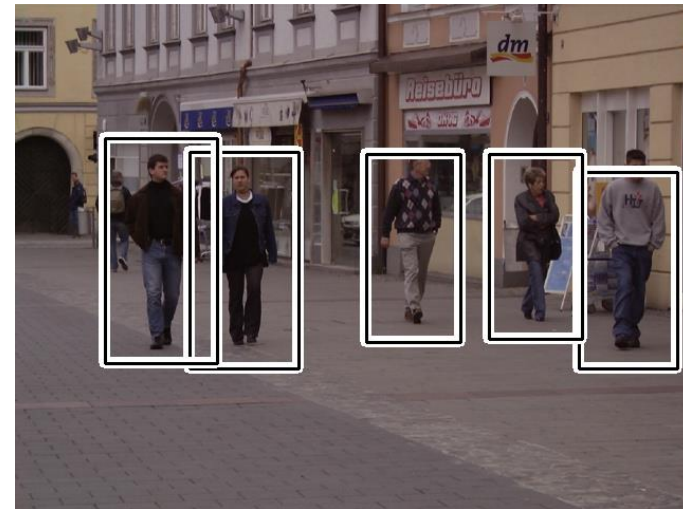
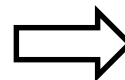
- Sliding Window



Feature Vector  
(properties of object)



Trainable Classifier  
(SVM, ANNs, ...)



# Face Detection

## Face Detection in OpenCV using cascade classifier

### 1. Rectangle (Haar features):

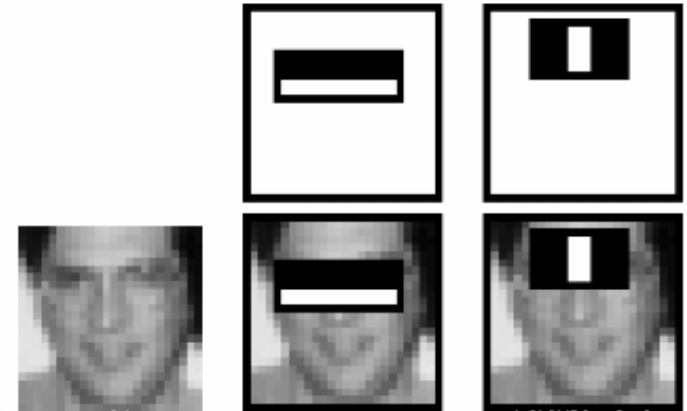
- faces have similar properties
- eye regions are darker than the upper-cheeks
- the nose bridge region is brighter than the eyes
- thousands possible

### 2. Integral Image

- speed the computational process

### 3. Cascade Classifier + AdaBoost

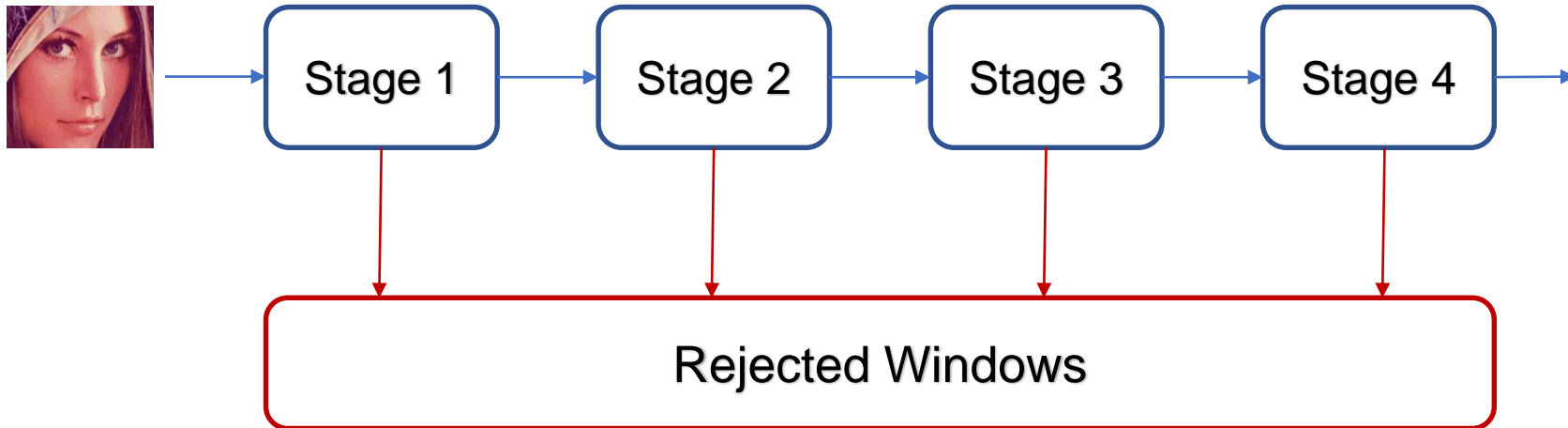
- in an image, most of the image is non-face region
- reject the non-face region as soon as possible





## Cascade of Classifier

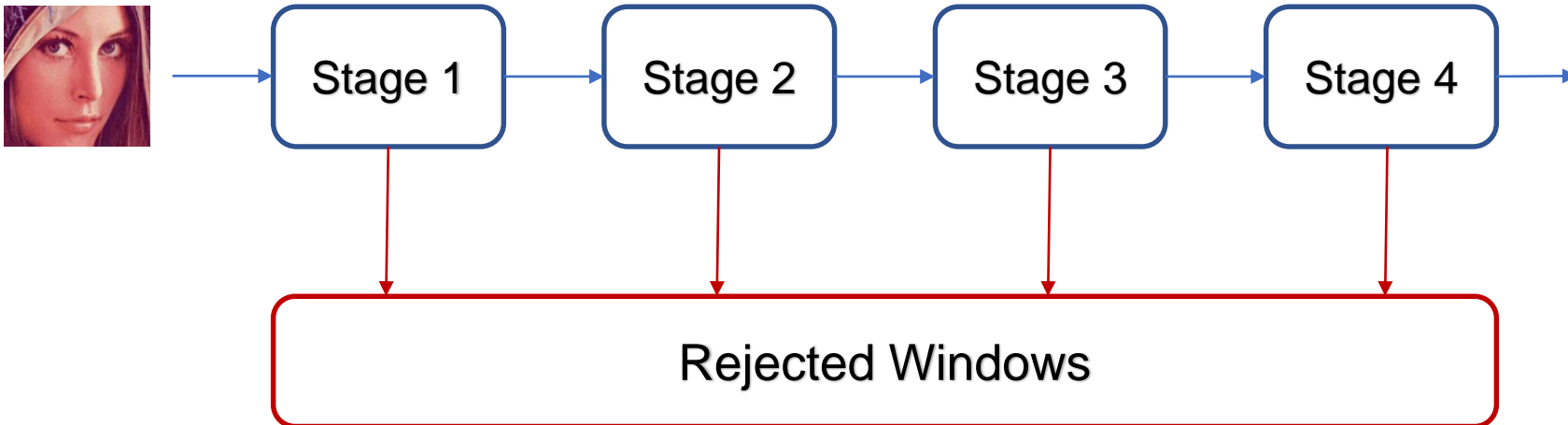
The idea of cascade classifier is reject the non-face region as soon as possible



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

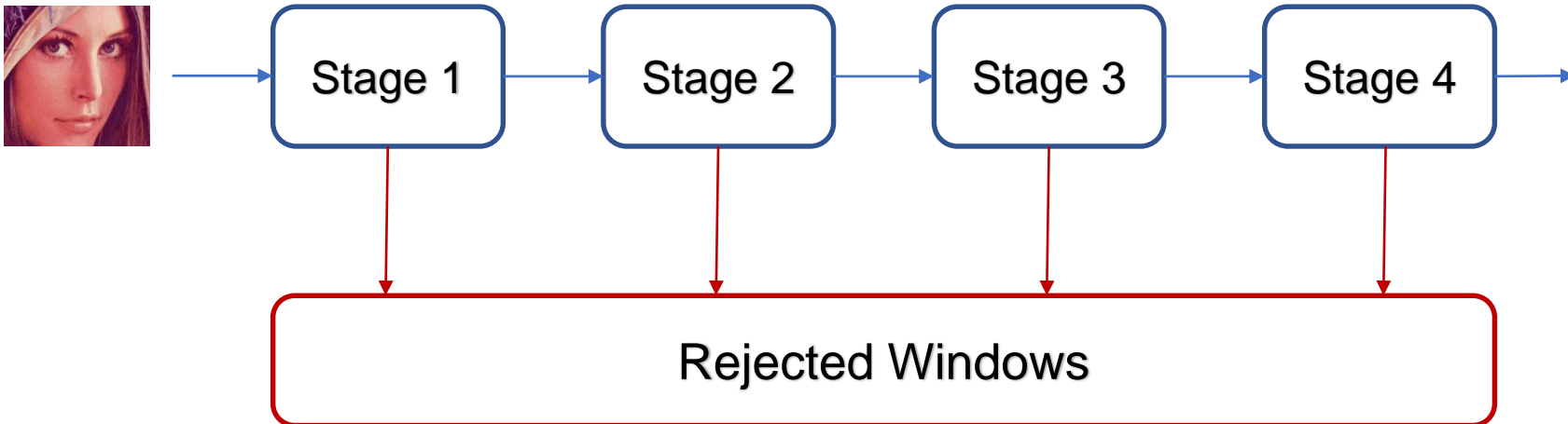
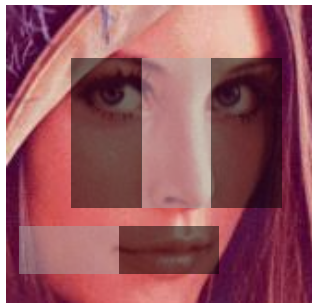
## Cascade of Classifier



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

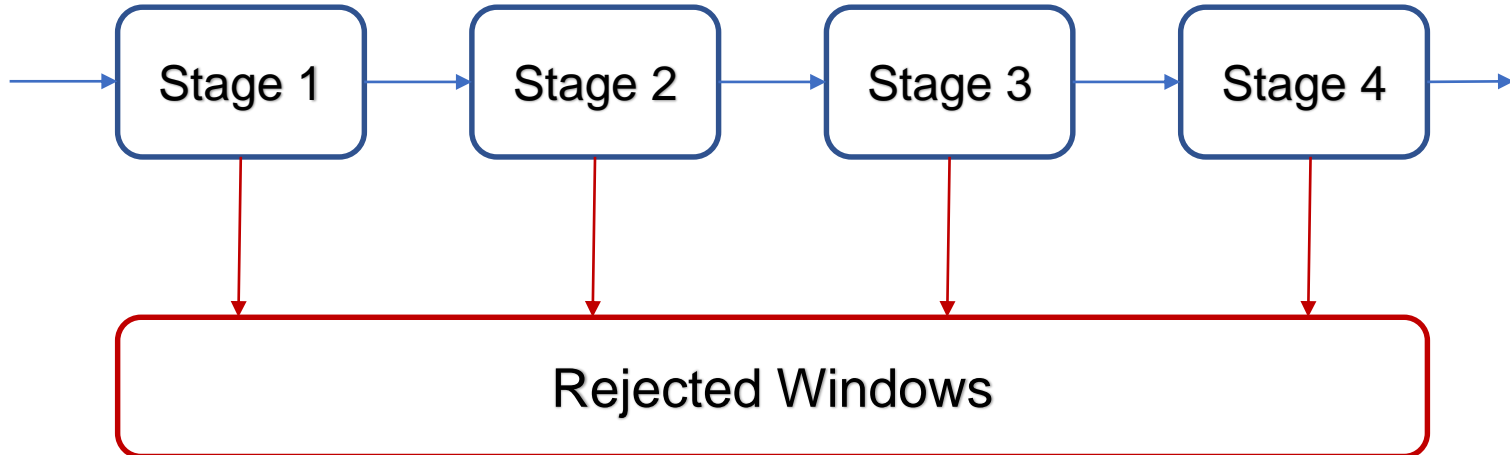
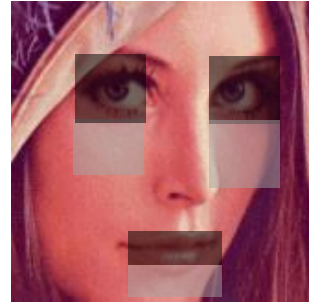
## Cascade of Classifier



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

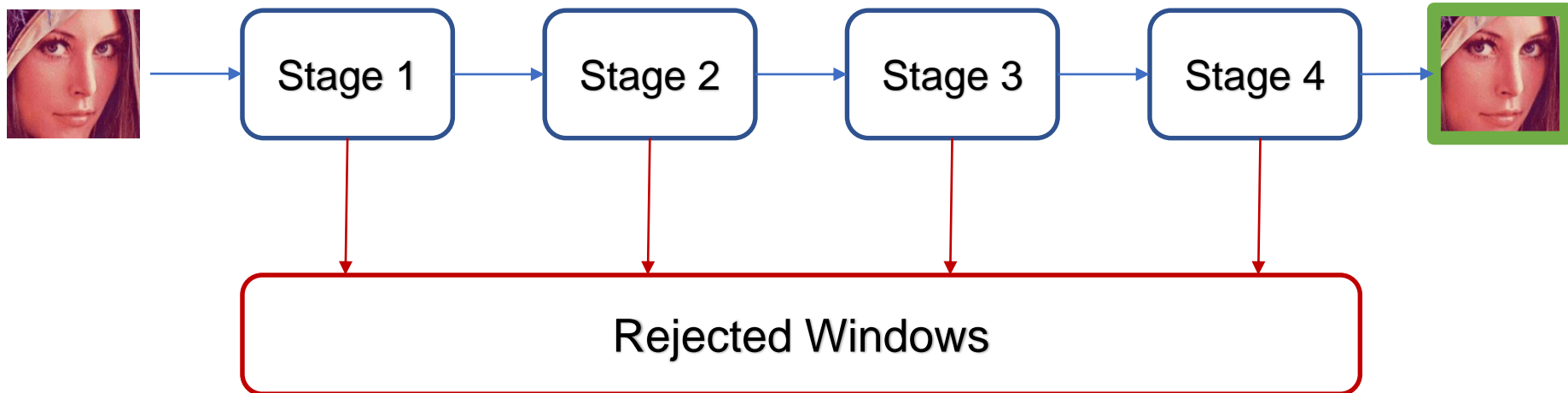
## Cascade of Classifier



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

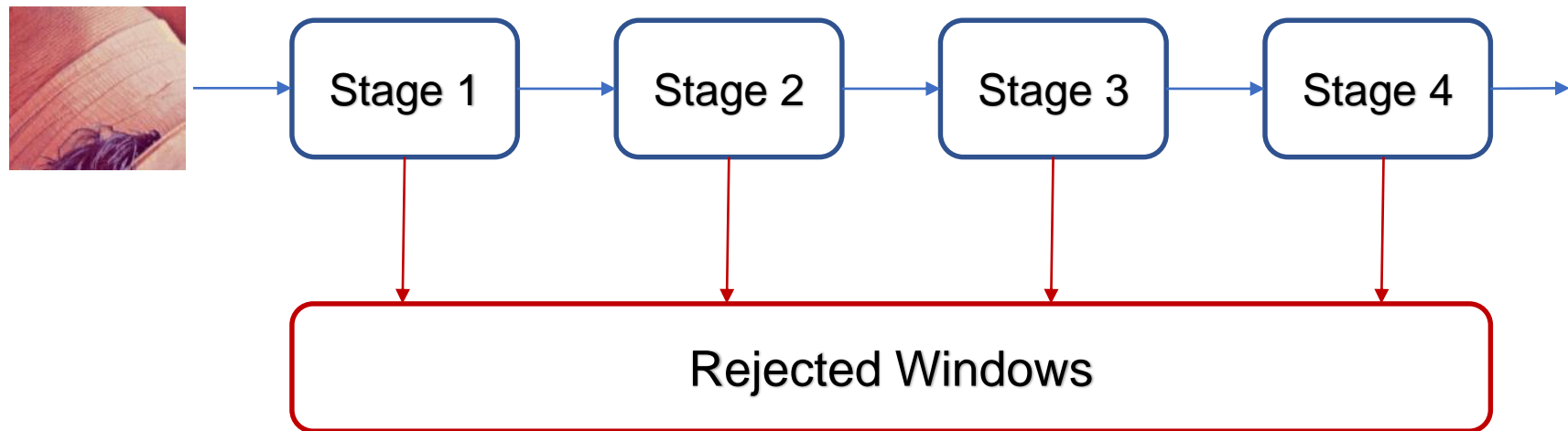
## Cascade of Classifier



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

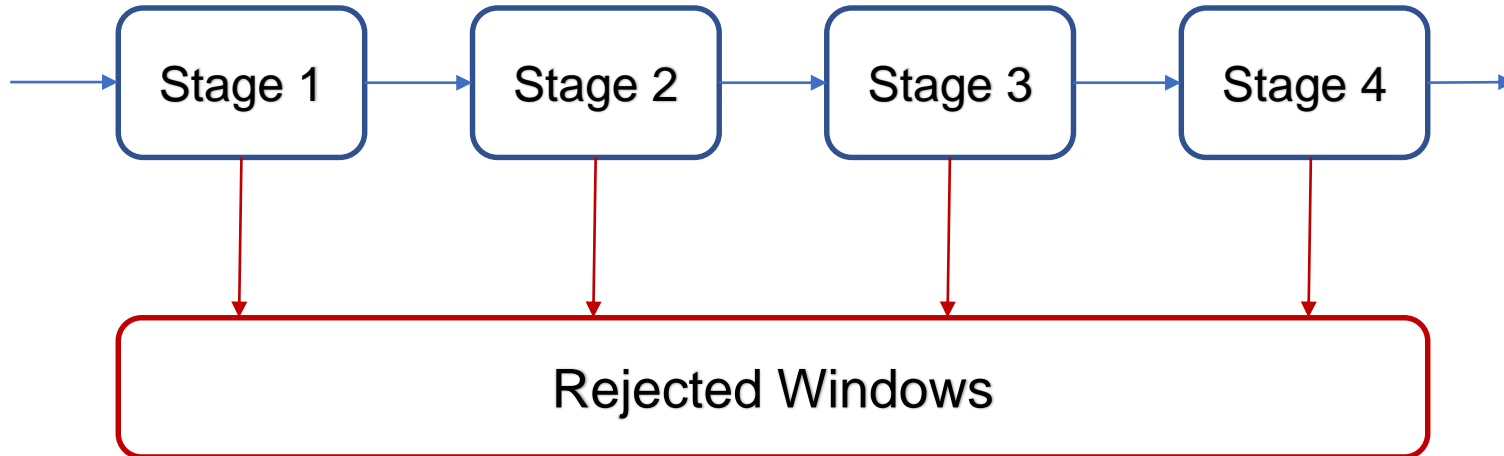
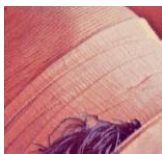
## Cascade of Classifier



# Face Detection

The idea of cascade classifier is reject the non-face region as soon as possible

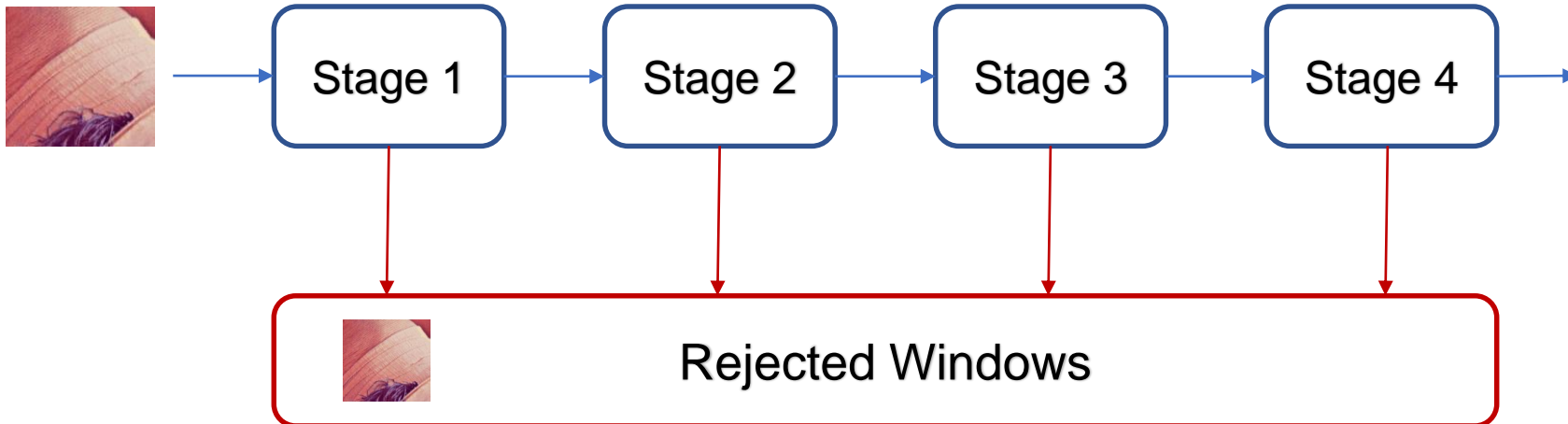
## Cascade of Classifier



# Face Detection

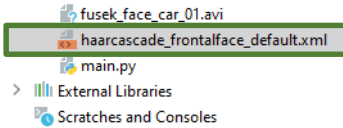
The idea of cascade classifier is reject the non-face region as soon as possible

## Cascade of Classifier









```

4
5 def face_detect():
6     cv2.namedWindow("face_detect", 0)
7     video_cap = cv2.VideoCapture("fusek_face_car_01.avi")
8     face_cascade = cv2.CascadeClassifier("haarcascade_frontalface_default.xml")
9
10    while True:
11        ret, frame = video_cap.read()
12        paint_frame = frame.copy()
13        if ret is True:
14            faces = face_cascade.detectMultiScale(frame,
15                                                    scaleFactor=1.2,
16                                                    minNeighbors=3,
17                                                    minSize=(100, 100),
18                                                    maxSize=(500, 500))
19            for one_face in faces:
20                cv2.rectangle(paint_frame, one_face, (0, 0, 255), 12)
21                cv2.rectangle(paint_frame, one_face, (255, 255, 255), 4)
22
23        cv2.imshow("opencv_frame", paint_frame)
24        if cv2.waitKey(2) == ord("q"):
25            break

```

## Python:

```

cv.CascadeClassifier.detectMultiScale( image[, scaleFactor[, minNeighbors[, flags[, minSize[, maxSize]]]]) - objects
>
cv.CascadeClassifier.detectMultiScale2( image[, scaleFactor[, minNeighbors[, flags[, minSize[, maxSize]]]]) - objects,
> numDetections
cv.CascadeClassifier.detectMultiScale3( image[, scaleFactor[, minNeighbors[, flags[, minSize[, maxSize[, outputRejectLevels]]]]) - objects, rejectLevels,
> levelWeights

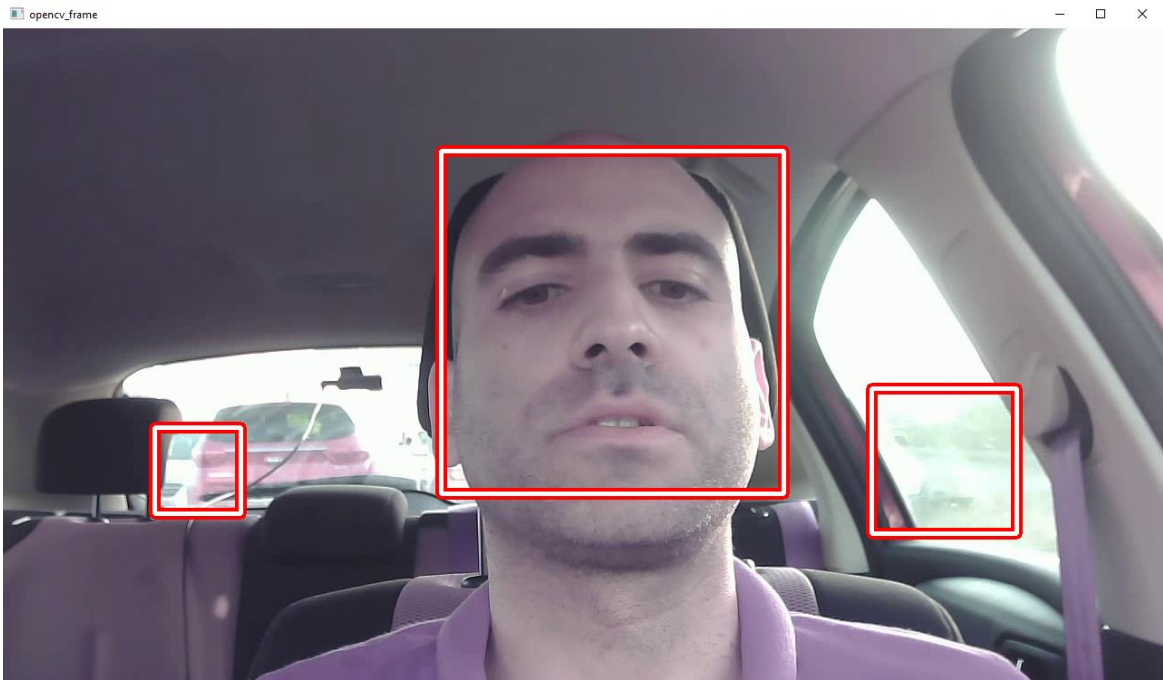
```

Detects objects of different sizes in the input image. The detected objects are returned as a list of rectangles.

## Parameters

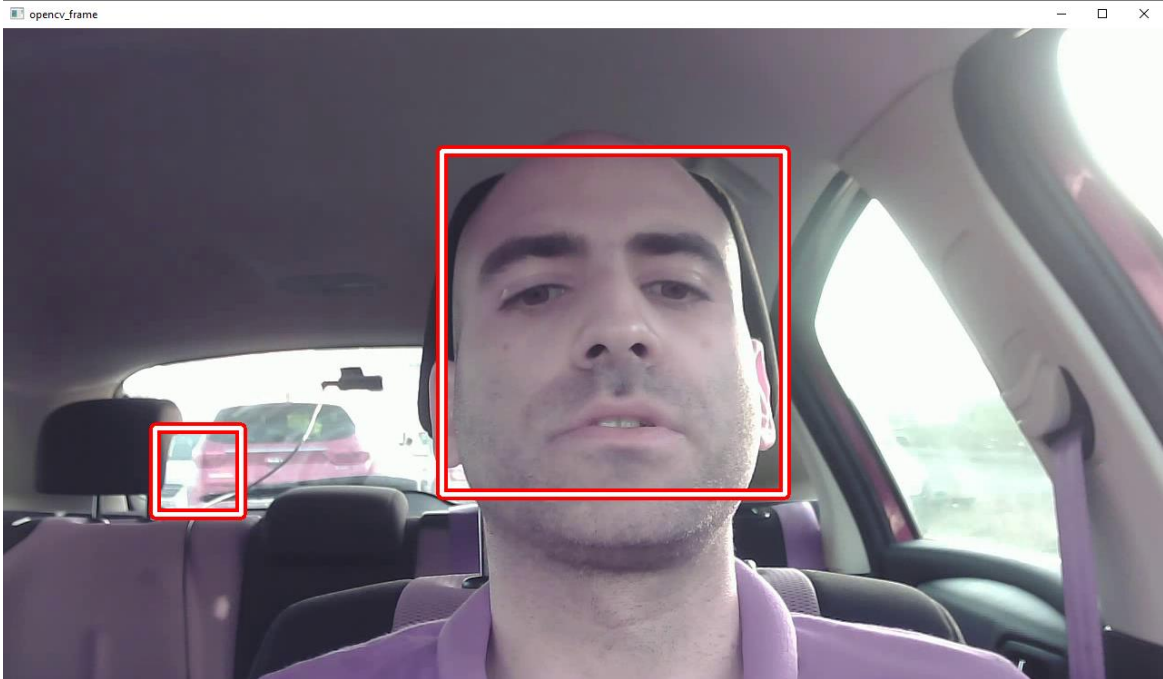
- image** Matrix of the type CV\_8U containing an image where objects are detected.
- objects** Vector of rectangles where each rectangle contains the detected object, the rectangles may be partially outside the original image.
- scaleFactor** Parameter specifying how much the image size is reduced at each image scale.
- minNeighbors** Parameter specifying how many neighbors each candidate rectangle should have to retain it.
- flags** Parameter with the same meaning for an old cascade as in the function cvHaarDetectObjects. It is not used for a new cascade.
- minSize** Minimum possible object size. Objects smaller than that are ignored.
- maxSize** Maximum possible object size. Objects larger than that are ignored. If `maxSize == minSize` model is evaluated on single scale.

# Face Detection - OpenCV



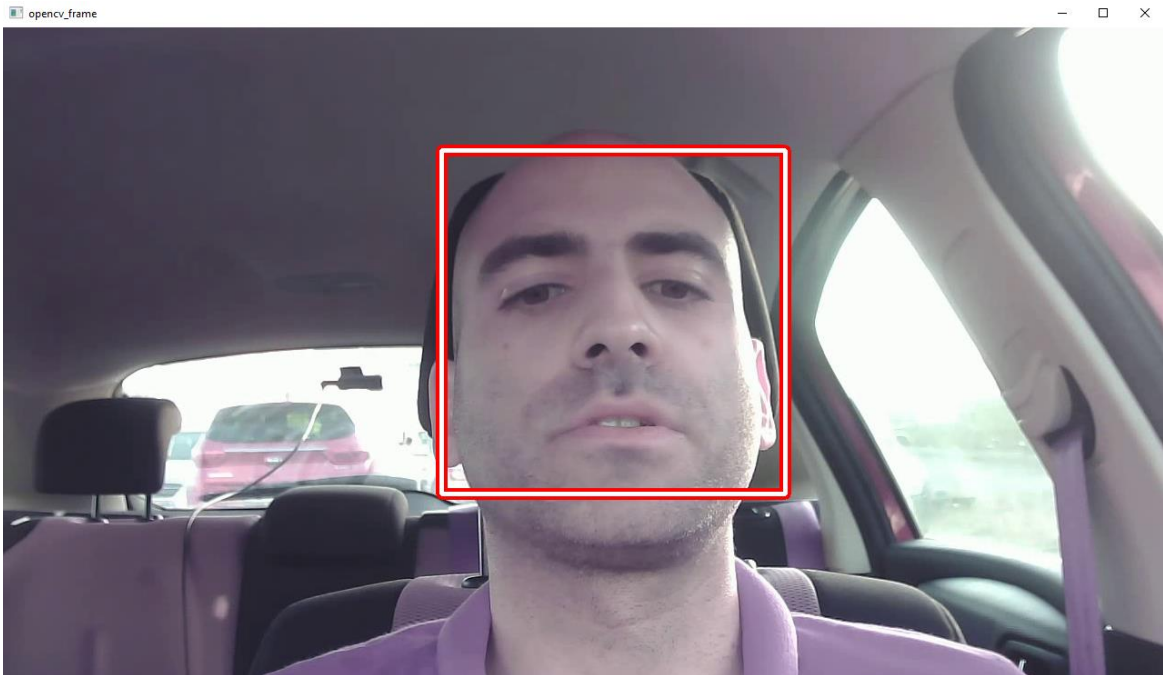
```
faces = face_cascade.detectMultiScale(frame,  
                                       scaleFactor=1.1,  
                                       minNeighbors=1,  
                                       minSize=(50, 50),  
                                       maxSize=(500, 500))
```

# Face Detection - OpenCV



```
faces = face_cascade.detectMultiScale(frame,  
                                     scaleFactor=1.1,  
                                     minNeighbors=3,  
                                     minSize=(50, 50),  
                                     maxSize=(500, 500))
```

# Face Detection - OpenCV



```
faces = face_cascade.detectMultiScale(frame,  
                                     scaleFactor=1.1,  
                                     minNeighbors=3,  
                                     minSize=(100, 100),  
                                     maxSize=(500, 500))
```